

# Efficient assembly of high order continuous and discontinuous finite element operators

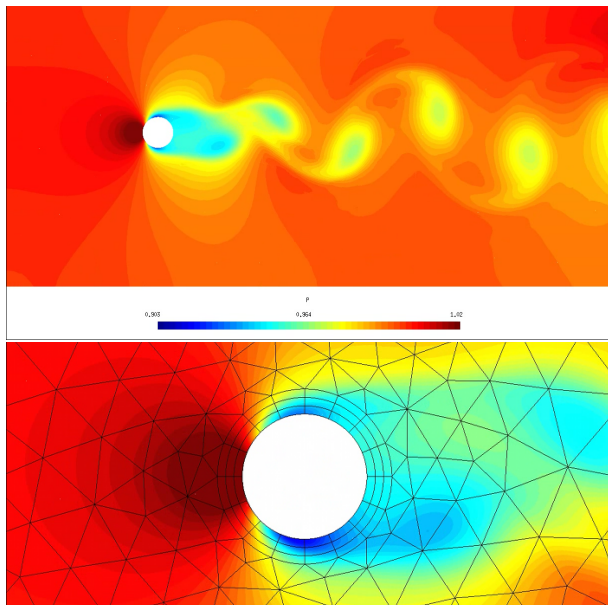
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# High order curved mixed meshes



# Formulation

## Continuous equation

$$0 = \nabla \cdot \mathbf{f}(u, \nabla u) + s(u, \nabla u)$$

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## Discrete formulation

$$u|_{\Omega_e} = \sum_j u_j^e \phi_j$$

$$0 = \underbrace{\int_{\Omega_e} -\mathbf{f}(u, \nabla u) \cdot \nabla \phi_i ds}_{F_i^e} + \underbrace{\int_{\partial\Omega_e} q(u^d, \nabla u^d) \phi_i dl}_{Q_i^e} \\ + \underbrace{\int_{\Omega_e} s(u, \nabla u) \phi_i ds}_{S_i^e}$$

$$i, j = 1, \dots, N ; e = 1, \dots, N_E ; d = 1, 2$$

$$S_i^e = \int_{\Omega_e} s(u) \phi_i ds \simeq \sum_{\xi} s^{e\xi} \phi_i^{\xi} w^{\xi} J^{e\xi} \quad \forall_i \forall_e$$

# Efficient numerical spatial integration

$$S_i^e = \int_{\Omega_e} s(u) \phi_i ds \simeq \sum_{\xi} s^{e\xi} \phi_i^{\xi} w^{\xi} J^{e\xi} \quad \forall_i \forall_e$$

1. evaluate the unknown field at the integration points

$$u^{e\xi} = \sum_i u_i^e \phi_i^{\xi} \quad \forall_e \forall_{\xi}$$

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1. evaluate the unknown field at the integration points  
 $u^{e\xi} = \sum_i u_i^e \phi_i^{\xi} \quad \forall_e \forall_{\xi}$
2. evaluate the conservation law and apply the mapping  
 $s^{e\xi} J^{e\xi} = s(u^{e\xi}) J^{e\xi} \quad \forall_e \forall_{\xi}$

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3. perform the integration on the parent element  
 $S_i^e \simeq \sum_{\xi} s^{e\xi} (u^{e\xi}) \phi_i^{\xi} w^{\xi} J^{e\xi} \quad \forall_e \forall_i$



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$$u^{e\xi} = \sum_i u_i^e \phi_i^{\xi} \quad \forall_e \forall_{\xi} \quad \mathcal{O}(N_E N_G N)$$

2. evaluate the conservation law and apply the mapping

$$s^{e\xi} J^{e\xi} = s(u^{e\xi}) J^{e\xi} \quad \forall_e \forall_{\xi} \quad \mathcal{O}(N_E N_G)$$

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$$S_i^e \simeq \sum_{\xi} s^{e\xi} (u^{e\xi}) \phi_i^{\xi} w^{\xi} J^{e\xi} \quad \forall_e \forall_i \quad \mathcal{O}(N_E N_G N)$$

In high order, operations 1 and 3 are expensive

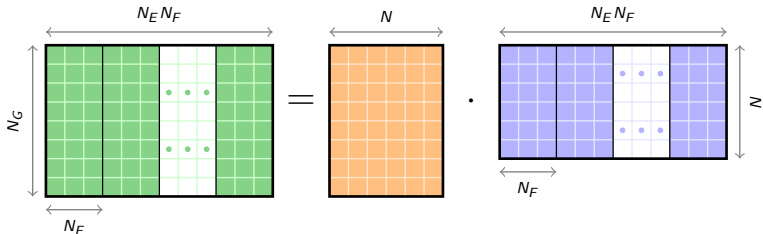
⇒ perform them as BLAS products.

# Evaluate the fields at integration points $\mathcal{O}(N_E N_G N)$

Recast costly operations as BLAS3 products

$$u_k^{e\xi} = \sum_i \underbrace{\phi_i^\xi}_{A[\xi][i]} \underbrace{u_{ki}^e}_{B[i][ek]} \quad \forall e \forall \xi$$

$$\mathbf{U} = \mathbf{A} \cdot \mathbf{B}$$



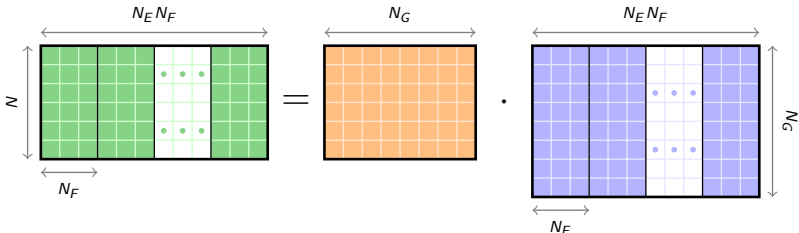
# Integrate over the parent element

 $\mathcal{O}(N_E N_G N)$ 

Recast costly operations as BLAS3 products

$$S_{ki}^e \simeq \sum_{\xi} \underbrace{\phi_i^{\xi} w^{\xi}}_{A[i][\xi]} \underbrace{S_k^{e\xi} J^{e\xi}}_{B[\xi][ek]} \quad \forall_i \forall_e$$

$$\mathbf{S} = \mathbf{A} \cdot \mathbf{B}$$



## Implicit : Evaluate the Jacobian matrix

$$F_{ki}^e = \int_{\Omega_e} -\mathbf{f}(u, \nabla u) \cdot \nabla \phi_i ds$$

$$\frac{dF_{ki}^e}{du_{lj}^e} = - \int_{\Omega_e} \left[ \frac{\partial \mathbf{f}_k}{\partial u_l} \frac{\partial u_l}{\partial u_{lj}^e} + \sum_b \frac{\partial \mathbf{f}_k}{\partial u_{l,x_b}} \frac{\partial u_{l,x_b}}{\partial u_{lj}^e} \right] \cdot \nabla \phi_i ds$$

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$$\approx - \sum_{\xi a} \left[ \frac{\partial f_{ka}^{e\xi}}{\partial u_l} \phi_j^\xi + \sum_b \frac{\partial f_{ka}^{e\xi}}{\partial u_{l,x_b}} \sum_\beta \phi_{j,\beta}^\xi Y_{b\beta}^{e\xi} \right] \sum_\alpha \phi_{i,\alpha}^\xi Y_{a\alpha}^{e\xi} w^\xi J^{e\xi}$$

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$$= - \sum_{\xi\alpha} \underbrace{w^\xi \phi_{i,\alpha}^\xi \phi_j^\xi}_{W_1[ij][\xi\alpha]} \underbrace{\sum_a \frac{\partial f_{ka}^{e\xi}}{\partial u_l} Y_{a\alpha}^{e\xi} J^{e\xi}}_{A_1[\xi\alpha][ekl]} - \sum_{\xi\alpha\beta} \underbrace{w^\xi \phi_{i,\alpha}^\xi \phi_{j,\beta}^\xi}_{W_2[ij][\xi\alpha\beta]} \underbrace{\sum_{ab} \frac{\partial f_{ka}^{e\xi}}{\partial u_{l,x_b}} Y_{a\alpha}^{e\xi} Y_{b\beta}^{e\xi} J^{e\xi}}_{A_2[\xi\alpha\beta][ekl]}$$

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$$\approx - \sum_{\xi a} \left[ \frac{\partial f_{ka}^{e\xi}}{\partial u_l} \phi_j^\xi + \sum_b \frac{\partial f_{ka}^{e\xi}}{\partial u_{l,x_b}} \sum_\beta \phi_{j,\beta}^\xi Y_{b\beta}^{e\xi} \right] \sum_\alpha \phi_{i,\alpha}^\xi Y_{a\alpha}^{e\xi} w^\xi J^{e\xi}$$

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- ▶ Four large *BLAS3* matrix-matrix products

$$\mathbf{K} \stackrel{\text{def}}{=} \mathbf{W}_1 \cdot \mathbf{A}_1 + \mathbf{W}_2 \cdot \mathbf{A}_2 + \mathbf{W}_3 \cdot \mathbf{A}_3 + \mathbf{W}_4 \cdot \mathbf{A}_4$$

$$\mathcal{O}(N_F^2 N^2 N_E N_G D)$$

- ▶ The entries have to be re-ordered

$$\mathbf{J}[ik][jl] = \mathbf{K}[ij][kl]$$

$$\mathcal{O}(N_F^2 N^2 N_E)$$

# Benchmark

Evaluation of the Jacobian matrix for continuous Galerkin 2D diffusion

5746 triangles

MacBook Pro @2600MHz (single threaded)

$p$	$t_{\text{old}}$	$t_{\text{new}}$
1	0.06	0.08
2	0.39	0.13
3	1.76	0.25
4	5.96	0.39
5	16.51	0.61
6	42.51	0.95
7	96.47	1.43
8	196.49	2.33
9	373.01	4.28



# Benchmark

Evaluation of the Jacobian matrix for continuous Galerkin 2D diffusion

5746 triangles

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$p$	$t_{\text{old}}$	$t_{\text{new}}$	$t_{\text{solver}}$
1	0.06	0.08	0.06
2	0.39	0.13	0.41
3	1.76	0.25	0.93
4	5.96	0.39	1.60
5	16.51	0.61	2.39
6	42.51	0.95	3.78
7	96.47	1.43	5.13
8	196.49	2.33	7.45
9	373.01	4.28	10.13

# Benchmark

Evaluation of the Jacobian matrix for continuous Galerkin 2D diffusion

5746 triangles

MacBook Pro @2600MHz (single threaded)

$p$	$N_G N^2$	$t_{\text{old}}$	$t_{\text{new}}$	$t_{\text{solver}}$
1	36	0.06	0.08	0.06
2	252	0.39	0.13	0.41
3	1,300	1.76	0.25	0.93
4	4,275	5.96	0.39	1.60
5	11,907	16.51	0.61	2.39
6	29,008	42.51	0.95	3.78
7	62,208	96.47	1.43	5.13
8	123,525	196.49	2.33	7.45
9	220,825	373.01	4.28	10.13

# Benchmark

Evaluation of the Jacobian matrix for continuous Galerkin 2D diffusion

5746 triangles

MacBook Pro @2600MHz (single threaded)

$p$	$N_G N^2$	$t_{\text{old}}$	$r_{\text{old}}$	$t_{\text{new}}$	$t_{\text{solver}}$
1	36	0.06	167	0.08	0.06
2	252	0.39	155	0.13	0.41
3	1,300	1.76	135	0.25	0.93
4	4,275	5.96	140	0.39	1.60
5	11,907	16.51	139	0.61	2.39
6	29,008	42.51	147	0.95	3.78
7	62,208	96.47	156	1.43	5.13
8	123,525	196.49	160	2.33	7.45
9	220,825	373.01	169	4.28	10.13

$$r = \frac{t}{N_G N^2} 10^5$$

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Evaluation of the Jacobian matrix for continuous Galerkin 2D diffusion

5746 triangles

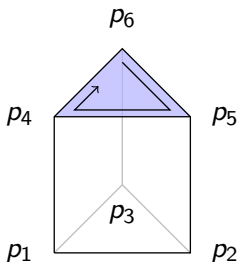
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1	36	0.06	167	0.08	220	0.06
2	252	0.39	155	0.13	52	0.41
3	1,300	1.76	135	0.25	20	0.93
4	4,275	5.96	140	0.39	9.1	1.60
5	11,907	16.51	139	0.61	5.1	2.39
6	29,008	42.51	147	0.95	3.3	3.78
7	62,208	96.47	156	1.43	2.3	5.13
8	123,525	196.49	160	2.33	1.9	7.45
9	220,825	373.01	169	4.28	1.9	10.13

$$r = \frac{t}{N_G N^2} 10^5$$

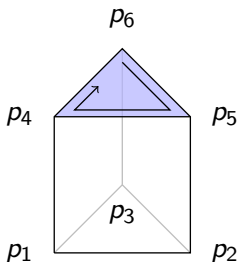
## Interface terms

Contributions from all faces with identical face-volume relative position are computed with one single BLAS product.

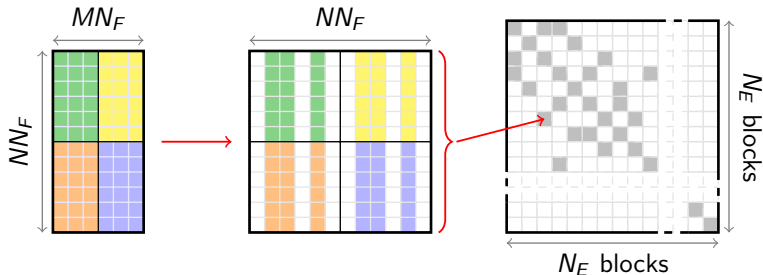


# Interface terms

Contributions from all faces with identical face-volume relative position are computed with one single BLAS product.



Matrix assembled by blocks



# Discontinuous benchmark

Evaluate and assemble the Jacobian matrix

Discontinuous Galerkin 3D advection/diffusion

MacBook Pro @2600MHz (single threaded)

$p$	time/ $N_E$	interface
1	$5.3 \cdot 10^{-5} \text{ s}$	71.7 %
2	$1.1 \cdot 10^{-4} \text{ s}$	62.5 %
3	$3.1 \cdot 10^{-4} \text{ s}$	51.1 %
4	$9.2 \cdot 10^{-4} \text{ s}$	40.4 %
5	$3.5 \cdot 10^{-3} \text{ s}$	26.6 %
6	$1.1 \cdot 10^{-2} \text{ s}$	19.9 %
7	$3.1 \cdot 10^{-2} \text{ s}$	15.2 %
8	$1.1 \cdot 10^{-1} \text{ s}$	9.4 %

# Conclusion

- ▶ Recipe to efficiently compute high order FE integrals
- ▶ No compromise on integration precision
- ▶ 7 times faster for P3 triangles
- ▶ 90 times faster for P9 triangles